



ShaRPY: Shape Reconstruction and Hand Pose Estimation From RGB-D with Uncertainty

Vanessa Wirth, A. Liphardt, B. Coppers, J. Bräunig, S. Heinrich, S. Leyendecker, A. Kleyer, G. Schett, M. Vossiek, B. Egger, and M. Stamminger

Contributions

First markerless RGB-D approach tailored to medical applications

Focus on plausibility of motions

- Speculated hidden parts
- Speculated skeleton
- Misclassified predictions

Keypoint-based SOTA [2,3]

Focus on reliability of motions with Uncertainty Estimation

ShaRPY

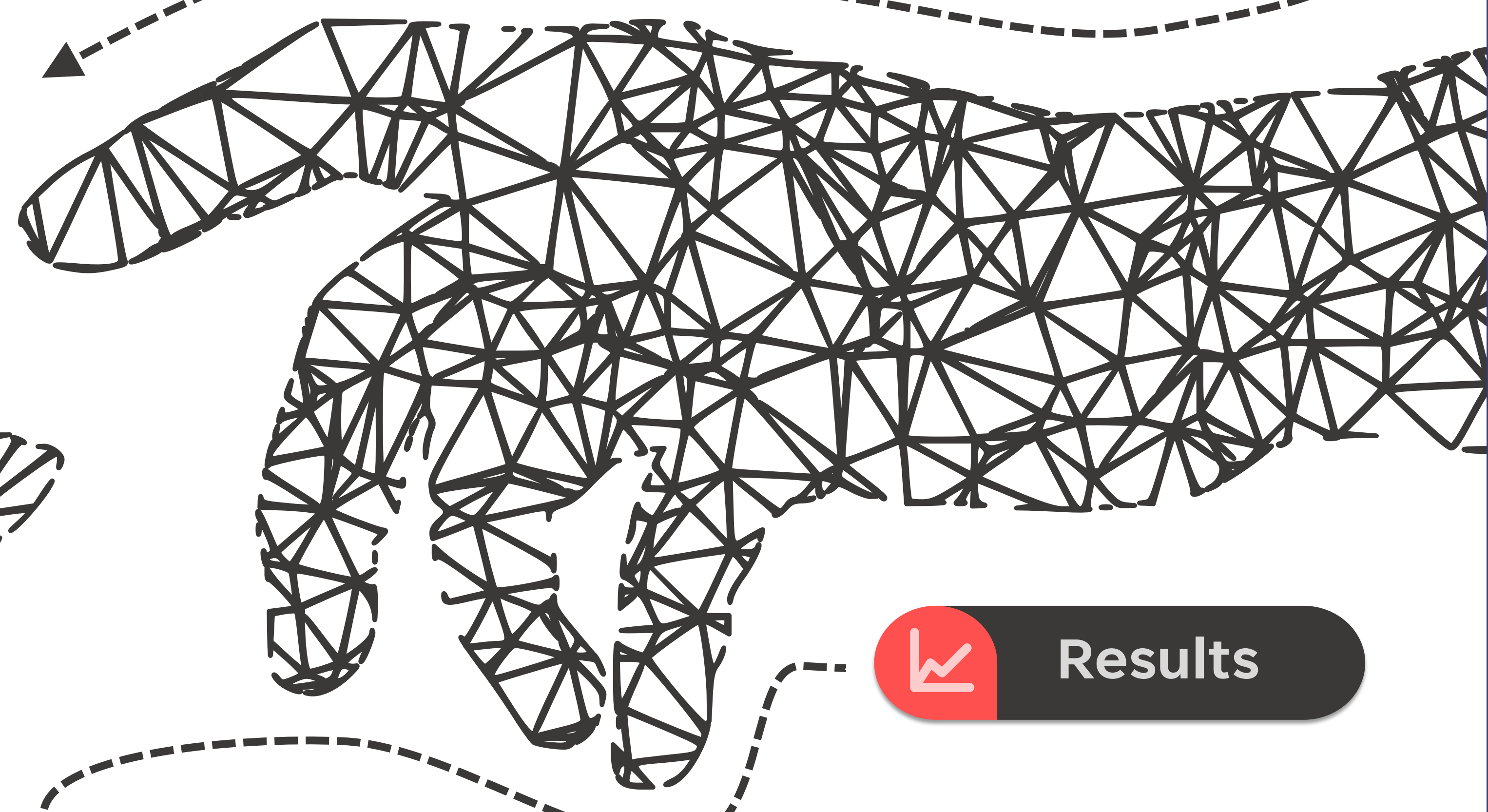
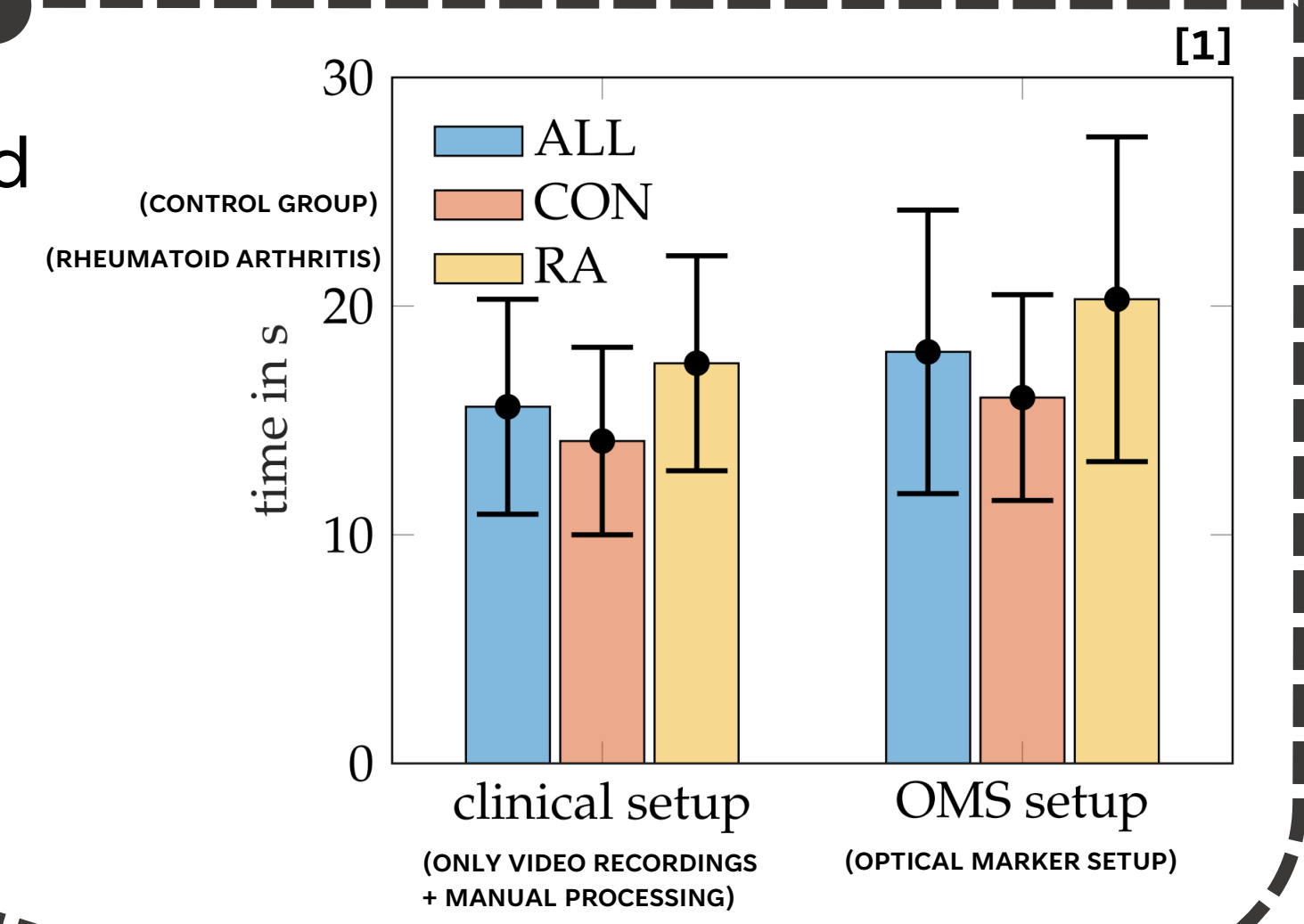
Intuitive 3D visualization of pose and personalized hand shape

Single RGB-D Camera (arbitrary model)

Motivation

Musculoskeletal diseases on the hand can be detected through motion. How can we objectively evaluate the hand function of a patient? Current SOTA with OMS is time-consuming and not intuitive → Markerless methods

START HERE



Results

Evaluation on H2O Pose Estimation

| | MEPE (mm) ↓ | | 3D PCK@15mm ↑ | |
|--------------------------------|--------------|--------------|---------------|--------------|
| | Left | Right | Left | right |
| Hasson et al. (CoRR 2020) | 39.56 | 41.87 | - | - |
| Tekin et al. (CVPR 2019) | 41.32 | 38.86 | - | - |
| Kwon et al. (ICCV 2021) | 41.45 | 37.21 | - | - |
| Aboukhandra et al. (WACV 2023) | 36.80 | 36.50 | - | - |
| Cho et al. (CVPR 2023) | 24.40 | 25.80 | - | - |
| Wen et al. (CVPR 2023) | 35.02 | 35.63 | 12.67 | 2.98 |
| Cho et al. (HBHA@ECCV 2022) | 14.40 | 15.90 | 70.75 | 54.61 |
| Luo et al. (HBHA@ECCV 2022) | 20.80 | 24.70 | 40.77 | 32.29 |
| Ours | 20.47 | 19.07 | 21.04 | 27.81 |

ShaRPY achieves 2nd place w.r.t. MEPE

Methods

Neural Object Detector

Depth Map

Correspondence Matching

Pose and Shape Tracking

Uncertainty Estimation

re-use temporal information $k-1 \rightarrow k$

RGB Image

unobserved

error-prone

Optimal Params $\Omega^k = (R^k, t^k, \theta^k, \beta^k)$

$\arg \min_{\Omega^k}$

$E_{3d}(C_{3d}) + E_{2d}(C_{2d}) + E_{shape}(\beta) + E_{pose}(\theta) + E_{temp}(\theta^{t-1}, \theta^t)$

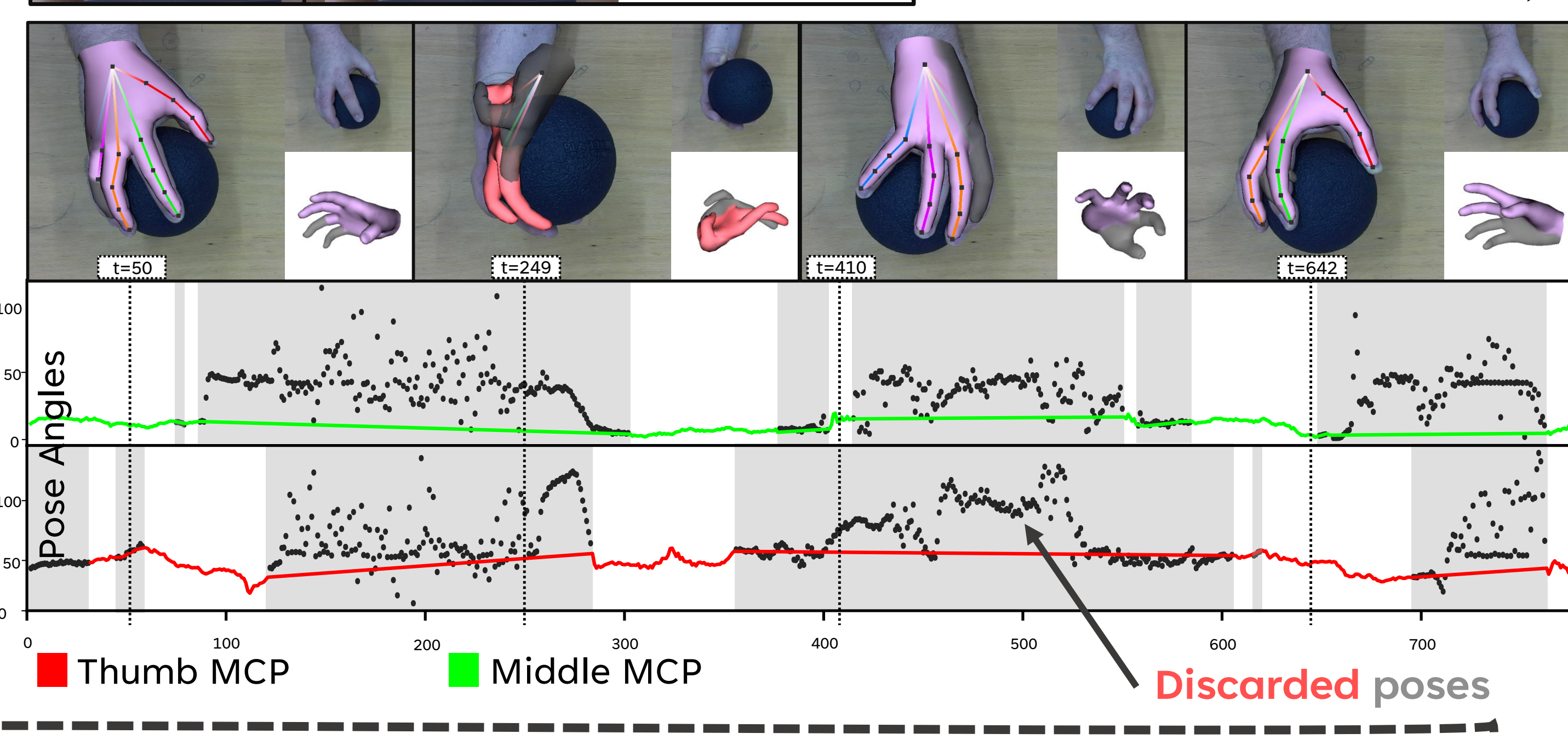
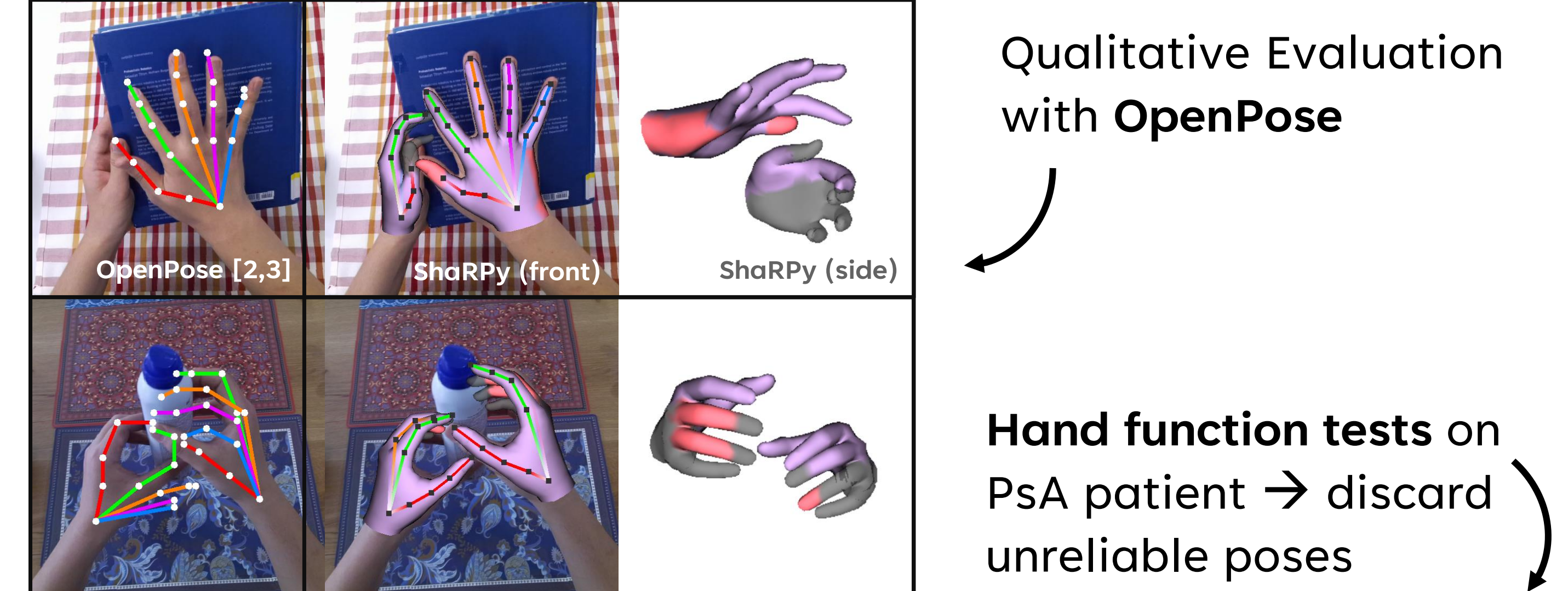
Ground truth (GT)

Prediction

Predicted Inconsistencies yield high or no residuals → Cluster residuals per segment → Thresholding → Error-prone & unobserved segments

Anatomically aligned Segmentation canonical correspondence space (H, S, V)

direct conversion



[1] U. Phutane et al.: Evaluation of Optical and Radar Based Motion Capturing Technologies for Characterizing Hand Movement in Rheumatoid Arthritis—A Pilot Study (Sensors 2021)
 [2] Z. Cao et al.: OpenPose: Realtime Multi-Person 2D Pose Estimation using Part Affinity Fields (TPAMI 2019)
 [3] T. Simon et al.: Hand Keypoint Detection in Single Images using Multiview Bootstrapping (CVPR 2017)